

## Retrieved tropospheric and stratospheric BrO columns over Lauder, New Zealand

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[1] Spectroscopic measurements of BrO using direct sun and zenith-sky viewing geometries are combined in an optimal estimation retrieval algorithm to obtain tropospheric and stratospheric columns of BrO. Seventy-two twilight periods are investigated over Lauder, New Zealand (45.0°S, 169.7°E), between March 2001 and April 2003. A direct comparison between tropospheric and stratospheric columns retrieved at 80°, 84°, and 87° solar zenith angles (SZAs) from the spectroscopic measurements and those calculated by the three-dimensional chemical transport model SLIMCAT shows good agreement. The stratospheric Br<sub>y</sub> loading of 21 pptv from the SLIMCAT calculations is consistent with the ground-based measurements. The seasonal and diurnal variation of the stratospheric BrO columns evident from the ground-based measurement retrievals is well described by the SLIMCAT model. The tropospheric column retrievals illustrate a high variability with a mean value of 0.2 pptv if the troposphere is assumed to be well mixed. An upper limit of 0.9 pptv is established for the ubiquitous BrO tropospheric column at 80° under cloud free conditions. *INDEX TERMS*: 0341 Atmospheric Composition and Structure: Middle atmosphere—constituent transport and chemistry (3334); 0365 Atmospheric Composition and Structure: Troposphere—composition and chemistry; 0394 Atmospheric Composition and Structure: Instruments and techniques; *KEYWORDS*: remote sensing, bromine, troposphere, retrieval, diurnal variation

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### 1. Introduction

[2] Approximately half of the current stratospheric bromine loading is attributable to human activities [Schauffler *et al.*, 1999]. Bromine in the radical form bromine monoxide (BrO) plays a key role in stratospheric ozone depletion processes both at middle and polar latitudes. At southern midlatitudes reactions involving bromine account for ~25% of total ozone losses [Lee *et al.*, 2002].

[3] In the troposphere, very high concentrations of BrO have been observed in both the polar boundary layer [Frieß *et al.*, 1999; Wagner *et al.*, 2001; Hönninger and Platt, 2002; Avallone *et al.*, 2003] and above salt plains [Stutz *et al.*, 2002; Matveev *et al.*, 2001]. These high

bromine levels in the troposphere have been linked to the biogeochemical cycling of mercury [Schroeder and Munthe, 1998]. At midlatitudes a tropospheric background of 1–2 pptv has been inferred from several different platforms, i.e., ground-based zenith sky observations, balloon observations and satellite measurements of BrO [Harder *et al.*, 1998; Fitzenberger *et al.*, 2000; Van Roozendaal *et al.*, 2000, 2002; Mueller *et al.*, 2002]. BrO tropospheric columns derived from the Global Ozone Monitoring Experiment (GOME) indicate that a ubiquitous BrO background concentration of 0.5–2 pptv is present in the free troposphere above the remote, equatorial Pacific ocean at high Sun [Richter *et al.*, 2002].

[4] The ability to separate tropospheric and stratospheric trace gas concentrations is becoming increasingly important with our growing awareness of the very different processes in these two regions. Jiang *et al.* [1997] proposed that combining diffuse and direct sun spectroscopic measurements could provide tropospheric sensitivity to ozone. This principle has been developed further here to retrieve tropospheric and stratospheric BrO columns. Profile retrievals from ground-based UV visible spectroscopic measurements have been performed in the past for NO<sub>2</sub> and O<sub>3</sub> [Brewer *et al.*, 1973; Noxon, 1975; McKenzie *et al.*, 1991; Preston *et al.*, 1997] with varying degrees of retrieval complexity. A combined DOAS optimal estimation profile retrieval is performed here, with a complete characterization and error

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analysis. Several profiles at different SZAs are retrieved to account for the diurnal variation of the BrO profiles over the twilight period. This is similar to retrieving several profiles at different locations to account for the variation of trace gas profiles along a line of sight of limb sounding satellites [Livesey and Read, 2000; Kemnitzer et al., 2002].

## 2. SLIMCAT 3-D Model

[5] In this study we have used output from a simulation of the SLIMCAT three-dimensional (3-D) off-line chemical transport model (CTM) [Chipperfield, 1999]. The model has a detailed treatment of gas phase and heterogeneous stratospheric chemistry. The model temperatures and horizontal winds are specified from meteorological analyses and the vertical transport in the stratosphere is diagnosed from radiative heating rates. In the stratosphere the model uses isentropic coordinates and this has recently been extended down to the surface using hybrid  $\sigma - \theta$  levels. Full details of this new version of SLIMCAT will be given in a forthcoming paper (M. P. Chipperfield and P. Simon, manuscript in preparation, 2004). However, for the studies here, the model did not use any representation of tropospheric physics. The model run assumed the troposphere was instantaneously well mixed so that the mixing ratio profile of tracers in the troposphere (defined by the model levels with  $\theta < 380$  K and  $PV < 2 \times 10^{-6}$  SI units) was constant. Therefore the advantages here over previous SLIMCAT simulations is to remove the model boundary away from the tropopause region, rather than attempting to simulate bromine chemistry in the troposphere.

[6] In the run used here the model was integrated with a horizontal resolution of  $7.5^\circ \times 7.5^\circ$  and 20 levels extending from the surface to about 55 km. The model was forced by European Centre for Medium Range Weather Forecasts (ECMWF) analyses and the simulation started 1/1/1989. The model halogen loading was specified (as a mixing ratio in the surface layer) from observed tropospheric  $\text{CH}_3\text{Br}$  and halon loadings [e.g., World Meteorological Organization, 2003] with an additional 6 pptv contribution assumed from short-lived bromine sources. Accordingly, the stratospheric bromine loading around 2000 was about 21 pptv. Output was saved at 0 UT every 2 days and linearly interpolated to the location of Lauder from the nearest 4 gridpoints at each model output time. A 1-D column model (with the identical chemistry to the 3-D model) was then used to reconstruct the diurnal cycle for comparison with the observations.

[7] The tropopause was defined to be the lower altitude of the layer for which the decrease in temperature with altitude was less than  $2^\circ\text{C}$  per km above 500 hPa [Bodeker et al., 1998]. The SLIMCAT model layers in the run used here have a thickness of about 4 km in the tropopause region thus the tropospheric column was calculated only up to about 8–9 km. The tropospheric values derived from SLIMCAT are thus conservative, ensuring that part of the stratospheric BrO amount was not partitioned into the tropospheric column.

## 3. The Retrieval Method

[8] The details of the retrieval algorithm used to obtain tropospheric and stratospheric columns by combining zenith sky and direct sun mea

ents is described by Schofield et al. [2004]. This section provides a brief outline of the method.

[9] Optimal estimation [Rodgers, 2000] is the retrieval method employed here to invert the measurements  $\mathbf{y}$  into the desired state  $\mathbf{x}$ . Optimal estimation finds the solution which best takes into account the prior knowledge of the state  $\mathbf{x}_a$ , its error  $\mathbf{S}_a$ , the measurements  $\mathbf{y}$ , and their errors  $\mathbf{S}_e$ . The equation that is solved for a linear problem is written as:

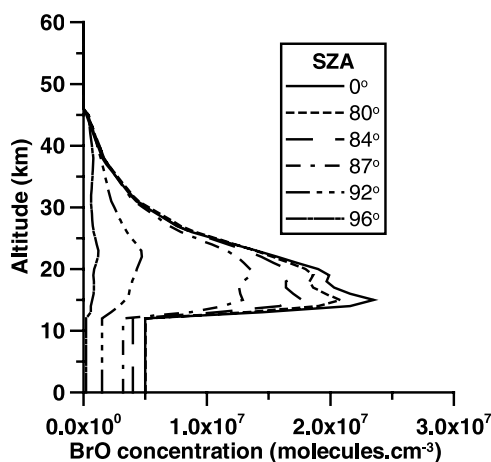
$$\hat{\mathbf{x}} = \mathbf{x}_a + \mathbf{S}_a \mathbf{K}^T (\mathbf{K} \mathbf{S}_a \mathbf{K}^T + \mathbf{S}_e)^{-1} (\mathbf{y} - \mathbf{K} \mathbf{x}_a). \quad (1)$$

[10] The matrix  $\mathbf{K}$  contains the weighting functions which describe the sensitivity of the forward model calculated differential slant column density (DSCD) values to changes in the state. The forward model atmosphere is defined using spherical geometry and divided into discrete atmospheric shells. The retrievals were conducted with the model atmosphere described up to 70 km, with 1 km model atmospheric layers. Only first-order scattering was included for the zenith sky viewing measurements. This was a reasonable assumption as the effects of multiple scattering on the zenith sky DSCDs for BrO are negligible up until about  $92^\circ$  [Sinnhuber et al., 2002; Perliski and Solomon, 1993]. Scattering due to attenuation only was assumed for the direct sun geometry. The effects of refraction, molecular absorption, Rayleigh and Mie scattering were included. The aerosol extinction profile for the stratosphere was provided by LIDAR and aerosol backscatter sonde data provided by J. B. Liley (unpublished data, 2003). Ozone, temperature and pressure profiles were provided from the ozonesonde measurements conducted at Lauder [Bodeker et al., 1998]. The  $\text{NO}_2$  profile was obtained over Lauder from Sage II (SAGE II  $\text{NO}_2$  profiles were supplied by the NASA Langley Research Center (NASA-LaRC) and the NASA Langley Radiation and Aerosols Branch, 2001–2003). As the forward model parameter errors were found to be negligible [Schofield et al., 2004] and to ensure consistency, constant forward model parameters (temperature, pressure, aerosol,  $\text{NO}_2$  profiles for day 254, 2001) were used for all retrievals over Lauder.

### 3.1. Construction of the State Vector

[11] The state vector  $\mathbf{x}$  describes what we wish to retrieve from the measurements. BrO has a strong diurnal variation and is converted into its nighttime reservoir at high SZA (believed to be predominantly  $\text{BrONO}_2$  at midlatitudes). The diurnal variation of the BrO profile complicates the choice of  $\mathbf{x}$ . A simple  $\mathbf{x}$  composed of a single profile of BrO would require that the diurnal variation be specified as a set of forward model parameters or a “hard constraint” within the retrieval problem. In this way the diurnal variation of the profile is specified from chemical models (either as a scalar multiple or more complex change of profile shape). However, all the irregularities in the chemistry are evident in the weighting functions, and propagate as errors into the final retrieved state.

[12] The diurnal change in the BrO profile was included in the state vector, thus avoiding these unnecessary errors. The state vector  $\mathbf{x}$  was constructed as a set of profiles defined on a SZA grid. Six profiles at the diurnal stages of  $0^\circ$ ,  $80^\circ$ ,  $84^\circ$ ,  $87^\circ$ ,  $92^\circ$  and  $96^\circ$  SZA were chosen to adequately describe the diurnal variation while minimizing the number of retrieval parameters. Retrieving the diurnal



**Figure 1.** The BrO profiles supplied as a priori information in all of the retrievals performed for Lauder.

variation of BrO in this way allows the direct comparison with the model derived columns.

[13] Displayed in Figure 1 are the a priori profiles used in the column retrievals for Lauder. The profiles are defined on a 1 km grid up to 70 km. The stratospheric diurnal variation was obtained from a stationary chemical stacked box model run over Lauder for sunset on day 254, 2001. The box model used stratospheric SLIMCAT [Chipperfield, 1999] chemistry with the most recent update of reaction rates [Sander *et al.*, 2000]. A constant tropospheric number density of  $5 \times 10^6$  molecules  $\text{cm}^{-3}$  was used in the construction of the  $0^\circ$  a priori, consistent with current estimates of an ubiquitous free tropospheric midlatitude BrO column from GOME [Richter *et al.*, 2002] ( $0.5$ – $2$  pptv) and from balloon flights [Fitzenberger *et al.*, 2000] ( $0.6$ – $3.7 \times 10^{13}$  molecules  $\text{cm}^{-2}$ ). In the absence of diurnal variation information or profile shape for midlatitude tropospheric BrO, a diurnal decrease in the tropospheric BrO concentration was assumed (similar to the decrease seen in the stratosphere).

### 3.2. Construction of the $S_a$ Matrix

[14] In the construction of  $S_a$ , 50% of the peak value (for each of the profiles in the a priori state vector) was used as the error (i.e., the square root of the diagonal of  $S_a$ ). 50% was chosen empirically to ensure the measurements were interpreted to provide the maximum amount of information, without interpreting measurement noise as information (for more details, refer to Schofield *et al.* [2004]).

[15] The retrieval problem defined here is formally ill-posed, with more state elements than independent measurements. The prior constraint and error ensures that an optimal solution of the state can be determined from the infinite set of possible solutions by providing information about the null and near null space of the weighting function matrix [Rodgers, 2000].

## 4. The Spectroscopic Measurements and DSCD Derivation

[16] The observation site Lauder ( $45.0^\circ\text{S}$ ,  $169.7^\circ\text{E}$ ) is located at an altitude of  $1200$  m above sea level in Central

Otago, New Zealand. Lauder is one of the five primary sites in the Network for the Detection of Stratospheric Change (NDSC). The DSCD values for BrO measured using two different viewing geometries, direct sun and zenith sky, were combined to create the measurement vector  $y$ . Owing to the complementary nature of these geometries, information about the state was accessed that would not be possible by considering each of these geometries independently. The stratospheric sensitivity was provided by the zenith sky geometry, while the tropospheric sensitivity was provided by the direct sun geometry. An unobscured Sun was requisite for the direct sun measurements introducing a clear-sky bias for the retrieved columns.

### 4.1. Instrumentation

[17] The direct sun spectrometer at Lauder was an Acton 275 (a commercial Czerny Turner spectrometer with spherical mirrors). The detector was a Hamamatsu back thinned charge coupled device (CCD) module with  $1044$  ( $24 \mu\text{m} \times 3100 \mu\text{m}$ ) pixels. The detector was cooled to  $-20^\circ\text{C}$ . The  $1200 \text{ gmm}^{-1}$  grating provides a wavelength coverage of  $324$ – $395$  nm at a resolution of  $0.5$  nm and FWHM sampling of about 7 pixels. The focal length was  $275$  mm and the focal ratio  $f/4.5$ . The sunlight was directed into the instrument using an active solar tracking system ( $10$  cm mirror  $-150 \text{ cm}^2$ ). A telescope lens focuses the incident light on a dichroic filter, which reflects light between  $325$ – $475$  nm into the instrument, to increase the dynamic range at shorter wavelengths. This light was then filtered using switchable neutral density filters on a filter wheel (providing factors of 0, 10, and 100 times attenuation) to extend the dynamic range over which measurements were made. The appropriate neutral density filter was selected based on light levels and integration time. A UG11 Schott filter attenuated light between  $400$ – $670$  nm to reduce stray light within the instrument. An integrating sphere was used at the entrance slit to ensure that the intensity across the field of view was homogenized. A field of view of  $1^\circ$  toward the Sun ensured the full Sun was always sampled despite small tracking errors. A National Instruments interface card together with a Lab-View program was used to collect, integrate and file spectra (with dark subtracted) at 180 second intervals. The dark current spectra were small compared to the signal spectra ( $<5\%$ ), so a simple subtraction was adequate.

[18] The zenith sky instrument conducting measurements at Lauder was a polarized flat field commercial Czerny-Turner spectrometer (ISA 320) that rotates in azimuth to keep the transmission axis of the Glan-Thompson polarizer (MUGTB12, Karl Lambrecht Corporation) mounted in front of the entrance slit normal to the Sun zenith plane. The photodiode array detector (pixel size  $25 \mu\text{m} \times 2500 \mu\text{m}$ ) was designed and built at the NOAA Aeronomy Laboratory [Mount *et al.*, 1992] and uses a 1024 element Reticon chip cooled to  $-80^\circ\text{C}$  (ensuring negligible dark current). The  $1200 \text{ gmm}^{-1}$  grating provided wavelength coverage of  $331$ – $390$  nm at a resolution of  $0.6$  nm and FWHM sampling of nearly 10 pixels. The focal length was  $320$  mm and the field of view was  $7^\circ$  ( $f/8$ ). Extensive baffling was added to the spectrometer to ensure that stray light was less than 1% for all sky conditions. Spectra were recorded with a fixed total integration interval of 300 s.

**Table 1.** Cross Sections and Fits Applied in the DOAS Spectral Fitting Procedure

	Geometries	Reference/Notes
O <sub>3</sub>	both	<i>Voigt et al.</i> [2001]
NO <sub>2</sub>	both	<i>Harder et al.</i> [1997]
BrO	both	<i>Wilmouth et al.</i> [1999]
O <sub>4</sub>	both	<i>Greenblatt et al.</i> [1990] 0.94 nm red shifted
Ring	zenith sky	measured
Ring/O <sub>3</sub>	zenith sky	second-order product
High pass filter	zenith sky	5 nm width
CH <sub>2</sub> O	direct sun	<i>Meller and Moortgat</i> [2000] 0.34 nm red shifted
Polynomials	direct sun	third order
Slope	direct sun	gradient >3

[19] Interpixel variability and etalon were not corrected as the spectral shift with respect to pixels was negligible over one twilight measurement period. This was due to both systems being temperature controlled and the reference spectra being generally close in time (3 hours) to the measurement spectra. All spectra were Gaussian filtered (with a typical  $\sigma$  of 3 pixels) thus further reducing the effect of interpixel variability. Tests on these effects showed no residuals above the photon noise. The spectra were wavelength calibrated with the Atlas Fraunhofer (Kitt Peak high resolution solar spectrum) using least squares fitting with the same cross sections that are applied in the DOAS spectral fitting.

#### 4.2. DOAS Analysis

[20] DSCD values from both direct sun and zenith sky viewing spectroscopic measurements were evaluated using the well-known DOAS technique (for a review of DOAS, see *Platt* [1994]). A ratio of the measured twilight and noon reference spectra removes the Fraunhofer structure present in these low-resolution solar radiance measurements after some additional corrections. In both the direct sun and zenith sky geometries noon reference spectra were chosen for each day (as close as possible to the local noon, yet still under cloud-free conditions). This meant that the DSCD range sampled by the measurements varied both between viewing modes and days. The broadband absorption

features and the Rayleigh and Mie scattering features that make up the spectral background baseline were removed by fitting low-order polynomials or a high pass filter. A nonlinear least squares fitting procedure was then employed to fit differential cross sections for each absorber, thus determining their respective absorptions [*Aliwell et al.*, 2002]. The cross sections and fits used in the determination of the DSCDs for both the direct sun and zenith sky geometries is given in Table 1. The “ring effect” due to rotational Raman scattering in the ratio spectra was taken into account by fitting a cross section [*Fish and Jones*, 1995]. The Ring cross section was derived from clear sky measurements at Lauder, for two polarization axes, parallel and normal to Sun zenith plane (known as the Schmeltekopf technique), similar to the method used by *Solomon et al.* [1987]. The fit of the BrO cross section to the measured absorption spectrum is displayed in Figure 2 for both the direct sun and zenith sky viewing geometries.

#### 5. Characterization and Error Analysis

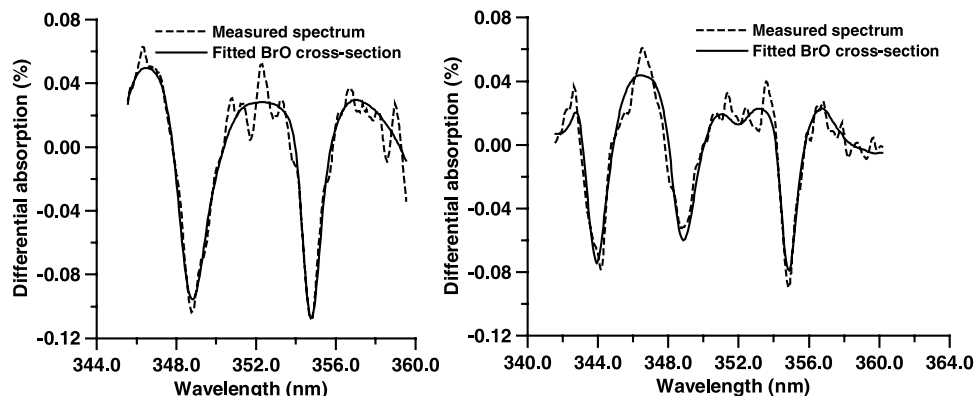
[21] Averaging kernels are one tool used in assessing how well the measured quantities describe the desired state. The averaging kernels describe the smoothing of the true state in the retrieval of each point and are evaluated with the following equation.

$$\mathbf{A} = \frac{\delta \hat{\mathbf{x}}}{\delta \mathbf{x}} = (\mathbf{K}^T \mathbf{S}_e^{-1} \mathbf{K} + \mathbf{S}_a^{-1})^{-1} \mathbf{K}^T \mathbf{S}_e^{-1} \mathbf{K} \quad (2)$$

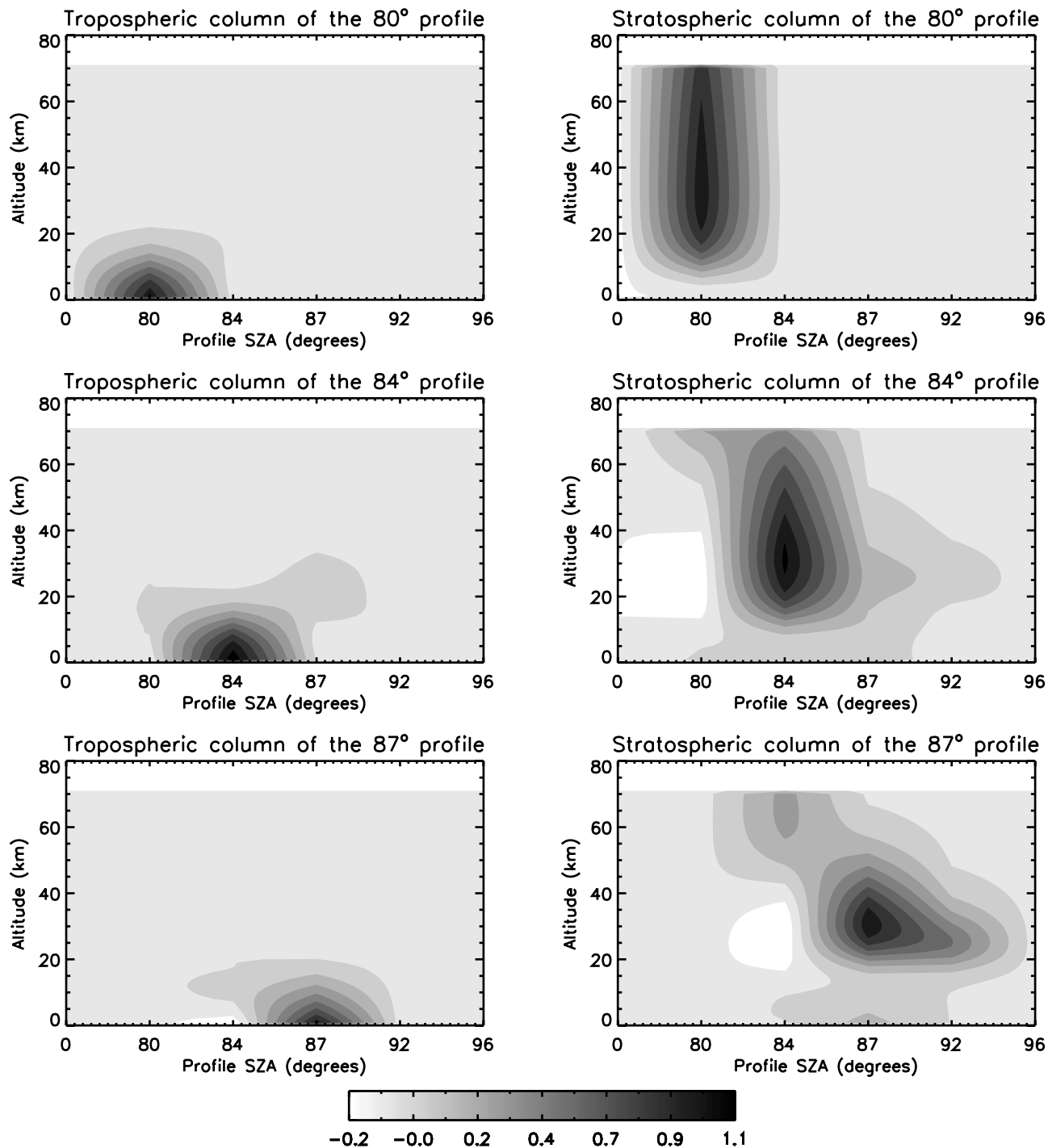
[22] The averaging kernels for the tropospheric and stratospheric columns for each of the six state profiles were evaluated from  $\mathbf{A}$  using a matrix  $\mathbf{g}$  which summed over the relevant altitudes in the state to give tropospheric and stratospheric columns for each of the six state profiles. The matrix  $\mathbf{g}$  is derived using the tropopause heights for each season. The column averaging kernels are given as:

$$\mathbf{A}_c = \mathbf{g} \mathbf{A}. \quad (3)$$

[23] Example averaging kernels for the retrieved columns  $\mathbf{A}_c$  are displayed in Figure 3. The averaging kernels for this



**Figure 2.** The left plot displays the BrO absorption spectrum measured with the direct sun viewing geometry at 87.3° at sunset on day 254, 2001. The right plot displays the zenith sky viewing geometry BrO absorption spectrum at 88.1° at sunset on day 254, 2001. The BrO cross-section fit to the measured absorption spe also displayed.



**Figure 3.** Example averaging kernels ( $A_c$ ) calculated in the characterization of the retrieval on the sunset on day 254, 2001. Only the averaging kernels for the 80°, 84°, and 87° columns, with high a priori independence, are displayed. The averaging kernels are two-dimensional as the retrieval is performed in altitude and SZA space.

retrieval are two-dimensional since 6 profiles are retrieved at different SZA. The averaging kernels are presented as contour plots. While contours give the impression of continuity, the values are discrete in both altitude and SZA (i.e., 1 km in altitude and 0°, 80°, 84°, 87°, 92° and 96° in SZA). The retrieved columns for the 0°, 92° and 96° SZAs were found to have a heavy a priori reliance with averaging kernels close to zero, these are not displayed in

Figure 3. The averaging kernels show that the retrieval of the tropospheric columns is clearly separate from the retrieval of the stratospheric columns. The retrieval of the 87° stratospheric column is the poorest (Figure 3, bottom right panel), with some of the retrieved value being obtained from the 92° profile and the upper stratosphere not being well represented. This is consistent with the higher retrieval errors for the 87° stratospheric column, as shown in Table 2.













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